

# Communication Satellite Satcom ABC series (2)



# Introduction

**Payload** 

Antenna

Transponder (LNA, D/C, IMUX, LCTWTA and OMUX)

CHINA APMT

Bus

TC&R Subsystem Electrical Power Subsystem Attitude Control Subsystem Thermal Control Subsystem Propulsion Subsystem



### Antennas

- C-band coverage
- Ku-band coverage
- Bent pipe transponders
  - Receiving and transmission

Payload

- Broadcasting service
  - TV broadcast
  - Internet access
  - Communication network
- Point to point service
  - Microwave radio relay technology
    As complements of terrestrial cables



### Bus

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### Platform

- The infrastructure providing locations for payload
- Telemetry and command subsystem
  - Communication with ground control station
  - Supporting tracking and ranging by ground stations
- Electrical power subsystem
  - Solar cells converting solar energy into electrical power
  - Batteries maintaining power during solar eclipse
- Attitude control subsystem
  - Keeping spacecraft in right orbit
  - Pointing antennas in right direction
  - Pointing solar arrays towards the sun

# Bus (cont.)

- Thermal control subsystem
  - Keeping all spacecraft parts within acceptable temperature ranges

- Propulsion subsystem
  - Bring spacecraft to desired orbit
  - As actuator for station keeping

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# **Antennas Onboard**

- Reflector Antennas
  - Simplest and most effective for FSS and BSS satellite
- Deployable reflector
  - 2 to 3 meters in diameter
  - Mounted on east and/or west side of S/C body
  - Stowed when launch and deployed in-orbit
  - Fine-tuning footprint pointing
- Steerable antenna
  - ➤ 1 to 1.5 meters in diameter
  - Mounted on earth deck of S/C body
  - Installed with wider moving range
    - ⇒ antenna pointing could be changed in limited directions

# Gain and Coverage

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### ✤ Antenna gain

- Defined as difference in power received by a directional antenna with an isotropic antenna in the same place sisotropic antenna: radiating same power at all directions
- dBi: decibel gain referenced to an isotropic antenna
   gain of isotropic antenna: 0dBi
- Antenna pattern
  - A map showing antenna designed specification by contour lines through points of equal antenna gains

# Gain and Coverage (cont.)

### Antenna pattern (cont.)

> Achieved by using multiple feeds system or shaped reflector



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# **Communication Payload**

### Transponder

Mainly operating in C-band (6/4 GHz) and Ku-band (14/12 GHz)

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### Basic functions

- Frequency translation
- Power amplification
- Noise filtering
- ✤ Modules
  - Antenna
  - Wideband receiver
    - $\Rightarrow$  LNA and D/C
  - Input and output multiplexer
  - ➤ LCTWTA

⇒ LCAMP (linearizer, FGM/ALC), TWTA

Redundancy

Receiver and LCTWTA

# **C-band Transponder Gain / Loss Budget**APMT



# Communication Payload (cont.) CHINA APMT

### Receiver

- ➤ LNA: low noise amplifier
  - ⇒ Noise figure: < 1.5dB (dominant of the entire system)
- D/C: down converter
  - $\Rightarrow$  C-band: 6 GHz to 4 GHz
  - $\Rightarrow$  Ku-band: 14 GHz to 12 GHz
- 60dB gain: to amplify input signal
- IMUX
  - Input Multiplexer
  - To divide total transmission bandwidth into frequency channels corresponding to the amplification chains
  - Selective filters
    - sufficiently steep slopes to avoid multiple paths through adjacent amplifying chains
    - ⇒ sufficiently flat response curve in the pass band to keep distortions to tolerable levels

# Communication Payload (cont.) CHINA APMT

### Linearizer

- Increasing linearity performance of the TWTA
- > Maintaining constant phase delay across entire channel
- Adjusting the overall transponder gain level



# Communication Payload (cont.) CHINA APMT

### TWTA

- Traveling wave tube amplifier
- Non-linear active device
- ➤ Typical gain of 50 to 60 dB

⇒ higher downlink power, higher C/N, higher receive quality

✤ OMUX

- Output Multiplexer
- > TWTA outputs combined together, then into transmit antenna
- Reject the out-of-band harmonics and spurious noises

# Ku-band Transponder Gain / Loss BudgetPMT



# Introduction

- **Payload** 
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# Telemetry, Command and Ranging INA APMT

### TC&R

- Telemetry, command and ranging
- Providing two-way information flow between S/C and E/S
- ✤ Telemetry
  - Gathering, processing and transmitting S/C data to control station so that S/C configuration and health can be monitored
- Command
  - Decoding and routing uplinked command to target units for S/C re-configuring, re-orienting or re-positioning
- Ranging
  - Providing a path to receive ranging tones and re-transmit them to originating ground control station
  - Range between E/S and S/C can be obtained by comparing phase difference between waveforms of transmit and receive tones

# **Telemetry**

### Telemetry circuit

- Gathering operational parameters
- Coding them into telemetry signals
- Transmitting them to the earth



# Command

### Tele-command circuit

- Receiving command signals from the earth
- Decoding the commands
- Distributing them to relevant subsystems



# Ranging

### Ranging circuit

Supporting satellite tracking and ranging by control station

**U**AZ

- Ranging loop
  - ⇒ receiving ranging tone from the earth
  - ⇒ constituting a loop circuit
  - $\Rightarrow$  transmitting it back to the earth  $2\lambda$

ranging by measuring range tone phase difference

3λ

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# **Electrical Power Subsystem**

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### DC power

- A capacity scale of satellite bus
- Typically 2 to 18 kW for communication satellites
- Power subsystem
  - Face-mounted solar panels
    - ⇒ convert solar energy into electrical power
    - ⇒ for payload and bus operation and battery charging
  - Regulator board and associated batteries
    storing and supplying power for usage in eclipse

# **Solar Arrays and Batteries**

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### Solar arrays

- 2 deployable solar wings
- Each wing consists of 3 to 5 panels
- Silicon solar cells: transfer solar energy to electricity
- Each panel is covered with solar cells (silicon or gallium arsenide) connected in series and in parallel
- Aligned with the earth's N-S axis
- Each wing is made to face the sun by an electric step motor which turns at 1rev./24hrs
- Rechargeable batteries
  - Power supply before solar wings deployed
  - Power supply in eclipse
    - $\Rightarrow$  charging at low rate with the sunlight
    - ⇒ discharging to provide electrical power during eclipse period



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# Yearly Variation of Solar Radiation Intersity

E

21 DEC

Solar radiation intensity

Vernal Equinox

21 MAR

See to be

Summer Solstice 21 JUN

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Sun

- Higher in vernal and autumnal equinoxes than in summer and winter solstices for the variation at sun light angle
   Higher in summer than in winter than in winter
- Higher in summer than in winter for the distances between the sun and the earth

Autumnal Equinox

22 SEP



# Life Variation of Solar Array PowerINA APMT

- Solar array power
  - Variation in every year
  - Low down in life time



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# **On-station Coordinates**

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Center of

Pitch Asis

Yaw Asta

- Three-dimensional coordinates
  - Carry forward the axes to control the attitude of a plane
- ✤ Roll
  - Pointing to east, the direction of S/C flying to
  - Roll rotation: antenna coverage shifts to N/S
- ✤ Pitch TC&R antenna Ku band antenna Pointing to south yaw/earth Pitch rotation: antenna coverage pitch/south +Z roll/east shifts to E/W +X +Y Y In Orbit Configuration (Whole satellite) C band antenna Yaw Solar Array Pointing to the earth, the direction of S/C floating on Yaw rotation: antenna coverage spins CW/CCW

# **Attitude Control and Station Keeping APMT**

- Attitude and orbit control subsystem
  - Sensors: to measure vehicle orientation
  - Flight software: to offer control algorithm
  - Actuators: to re-orient the S/C, and keep orbital position
- Attitude control
  - Automatically executed by ACS
  - Earth-pointing: keeping antennas in the right directions
  - Sun pointing: positioning solar arrays towards the sun
- Station keeping
  - Manually ordered by TT&C station
  - To counteract the movement of a satellite witch be affected by the gravitational field of the sun, the moon, and the earth
  - The amount of movement can be predicted using some complicated mathematical equations

# **Equipments of ACS**

### Sensors

- To detect attitude and position data
- Gyro assembly and fiber optic gyro: offers roll and yaw angles

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- Sun sensor: transfer orbit
- Earth sensor: offers pitch and roll angles
- Star tracker: roll, yaw and pitch

### Actuators

- To apply the torques and forces needed to re-orient the vehicle to a desired attitude or in the correct orbital position
- Reaction wheels: used for attitude control
- Thrusters: used for station keeping
- Solar array drive mechanism: to keep arrays facing the sun

# **Equipments of ACS (cont.)**

### On-board processor

- Processing the information offered by sensors
  - $\Rightarrow$  accurate data collection
  - ⇒ subsequent data interpretation
- Selecting proper actuator
- Short propulsive maneuvers executed in the right direction
- Attitude corrected to accomplish precise pointing



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# **Thermal Environment**

### Vacuum environment

Presence of sun illumination, the temperature at S/C surface will heat up quickly

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- Absence of sun illumination especially during sun eclipse, it will fall down extremely
- Variation of solar irradiation
  - Daily and annually
  - ➤ Eclipse



# **Why Thermal Control**

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### Thermal control

- Can be composed both of passive and active items
- Protecting the equipment from too hot temperatures
   by thermal insulation from external heat fluxes
   or by proper heat removal from internal sources
- Protecting the equipment from too cold temperatures
   by thermal insulation from external sinks
   by enhanced heat absorption from external sources
   or by heat release from internal sources

### ✤ Reference

http://www.tak2000.com/data/Satellite TC.pdf

# **How Thermal Control**

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### Methods

Reflection

⇒ optical solar reflector, thermal control coating

Insulation

⇒ multi-layer insulation for external surface

Radiation

⇒ radiators on external N/S side to reject heat to space

Heating

heaters for propellant lines, thrusters, main engine, and other equipments from too cold environment

### Conduction

heat pipe spreading out heat generated by HPA and other internal active parts

# **Passive Thermal Control**

### ✤ MLI

- Multi-layer Insulation
- Protecting spacecraft from excessive heating and cooling

- ✤ OSR
  - Optical Solar Reflectors
  - Improving heat rejection capability of the external radiators
  - Reducing absorption of external solar flux
- Coating
  - Changing thermo-optical properties of external surfaces
- Thermal fillers
  - Improving thermal coupling at selected interfaces
- Thermal doublers
  - Spreading heat dissipation under unit and on the radiator surface

# **Active Thermal Control**

- Thermostatically controlled resistive electric heaters
  - Keeping equipment temperature above its lower limit during the mission cold phases

- Fluid loops
  - Transferring the heat dissipated by equipment to the radiators
  - Single-phase loop, controlled by a pump
  - Two-phase loops, composed of heat pipes (HP), loop heat pipes (LHP) or capillary pumped loops (CPL)
- Thermoelectric coolers
- Louvers
  - Changing heat rejection capability as a function of temperature

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# **Propulsion Subsystem**

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### Conventional propulsion subsystem

Fuel and tanks

⇒ launch mass: S/C weight at the beginning of life

⇒ dry mass: S/C weight at the end of life

- Pipes and valves
- Thrusters

⇒ keeping spacecraft in its assigned place in orbit
 ⇒ unloading momentum wheels

➤ Main engine

 $\Rightarrow$  bringing the spacecraft to its permanent position

- Thermal control
  - Monitoring component temperatures of propulsion subsystem
  - Preheating tanks and thrusters in preparation for a spacecraft maneuver

# **Function**

- Generating thrust and providing impulse
  - Firing at transfer orbit to achieve GEO orbit
- Providing impulse, maintaining S/C attitude and orbital position
  - During GEO operations
- Providing minimum impulse bits
  - During normal mode operation
  - For momentum wheel unloading
- Providing velocity change and attitude control
  - During station keeping maneuvers

# **Functional Parts**

### Pressure supply and regulation

- Helium tanks
  - ⇒ providing helium gas as pressurant
- Pressure regulation
  - pressurizing and regulating, valve checking and latching, helium filtering

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- Propellant storage and distribution
  - Propellant storage
    - ⇒ propellant tanks and management devices
  - Propellant distribution

⇒ pipes to LAE and thrusters

- Thrusters and main engine
  - ≻ LAE

⇒ liquid apogee engine

16 thrusters

⇒ for attitude and orbit control

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### **LAE and Thruster Plumes**



# CHINA APMT CHINA APMT Propulsion types gas chemical electrical

liquid

bipropellant

solid

mono-

propellant



### AsiaSat: Customer Training Materials, April 2004 Wikipedia

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# Thanks!

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